

Changelog

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---> MPlc Release 2.0 22Oct04

- BUGFIX: Solve problem of sporadic system error by a modified memory management
- BUGFIX: Sync engagement ability increased
- BUGFIX: Non standard encoder management (with number of pulses not power of 2)
- BUGFIX: The EMCY message now carry the error register with the specification of the occurred alarm
- NEW: Electronic nameplate
 When connected to a motor with Endat encoder the drive will automatic get all the motor parameters
- NEW: Hall sensor encoder management
- NEW: Number of pulses of the encoder simulation now settable from 1 to 8192 by step of power of 2
- NEW: Test routine added for encoder phasing (Sincos only) and current loop calibration
- NEW: Software manual release 1.3

---> MPlc Release 2.4 17Dec04

- BUGFIX: Feed-Forward angle managing
- BUGFIX: Simulated index

---> MPlc Release 3.0 7Oct05

- BUGFIX: encoder simulation startup error
- BUGFIX: hall sensor management evolution
- NEW: Auto set of encoder voltage supply for new drive hardware release B
- NEW: Added two system flags for Endat debugging
- NEW: parameters for limit the frequency of encoder simulation

---> MPlc Release 4.0 4Jul06

- BUGFIX: fan management evolution
- NEW: Added one system parameter for disabling the automatic encoder phasing on index signal

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