Type: Squid Torque Motor

TK370-xxx-yyy

NOTE:

(*) These dimensions can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition.

(**) Dimensions dependent on the motor winding configuration. General tolerances, geometrical/shape class (ISO 2768-2) class K and linear tolerance (ISO 2768-2) class M.

(***) Suggested position for hydraulic connectors.

(****) To calculate the minimum number of screws, use follows formulas:

\[ X = \text{Stack length} \times 0.147 \]

\[ Y = \text{Stack length} \times 0.194 \]

Calculation for screws property class 8.8. The number of screws can be reduced using higher property classes.

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