Type: Squid Torque Motor

TK120-xxx-yyy

NOTE:
(*) These dimensions can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition. (**) Dimensions dependent on the motor winding configuration. General tolerance: geometrical tolerance (ISO 2768-2) class K linear tolerance (ISO 2768-2) class M. (***) Suggested position for hydraulic connectors. (****) To calculate the minimum number of screws, use follows formulas:
X (N° Stator screw)= Stack length * 0.046
Y (N° Rotor crews)= Stack length * 0.09
Calculation for screws property class 8.8
The number of screws can be reduced using higher property classes.