Type: Squid Torque Motor

TK360-xxx-yyy

CABLING
To drive power output

Back EMF SEQUENCE
U - V - W
for rotor clockwise rotation
view from cable output
opposite side

NOTE:
(*) These dimensions can be increased for low polarity motors,
and must be confirmed together with detailed datasheet definition.
(**) Dimensions dependent on the motor winding configuration.
General tolerances: geometrical tolerance (ISO 2768-2) class K
linear tolerance (ISO 2768-2) class M.
(***) Suggested position for hydraulic connectors.
(****) To calculate the minimum number of screws, use the following formulas:
X (N° Stator screws) = Stack length * 0.068
Y (N° Rotor screws) = Stack length * 0.105
The number of screws can be reduced using higher property classes.