NOTE:
(*) These dimension can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition.
(**) Dimensions depend on the motor winding configuration.
General tolerance: geometrical tolerance (ISO 2768-2) class K linear tolerance (ISO 2768-2) class M.
(***) Suggested position for hydraulic connectors.
(****) To calculate the minimum number of screws, use follows formulas:
X (N° Stator screw)= Stack length * 0.053
Y (N° Rotor crews)= Stack length * 0.102
Calculation for screws property class 8.8.
The number of screws can be reduced using higher property classes.

Type: Squid Torque Motor
TK188-xxx-yyy