**NOTE:**

(*) These dimension can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition.

(**) Dimensions dependent on the motor winding configuration.

General tolerance: geometrical tolerance (ISO 2768-2) class K linear tolerance (ISO 2768-2) class M.

(***) Suggested position for hydraulic connectors.

(****) To calculate the minimum number of screws, use the following formulas:

- **X** (N° Stator screw) = Stack length * 0.038
- **Y** (N° Rotor crews) = Stack length * 0.043

Calculation for screws property class 8.8

The number of screws can be reduced using higher property classes.

**Type:** Squid Torque Motor

**TK260-xxx-yyy**