Type: Squid Torque Motor

TK240-xxx-yyy

NOTE:
(*) These dimension can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition. Dimensions dependent on the motor winding configuration. General tolerance: geometrical tolerance (ISO 2768-2) class K linear tolerance (ISO 2768-2) class M.
(**) Suggested position for hydraulic connectors.
(****) To calculate the minimum number of screws, use follows formulas:
X (N° Stator screw) = Stack lenght * 0.077
Y (N° Rotor screws) = Stack lenght * 0.122
Calculation for screws property class 8.8 The number of screws can be reduced using higher property classes.

Back EMF SEQUENCE
U - V - W
for rotor clockwise rotation view from cable output opposite side

CABLING
To drive power output