Type: Squid Torque Motor

TK195-xxx-yyy

**NOTE:**

(*) These dimension can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition.

(**) Dimensions depend on the motor winding configuration.

General tolerance: geometrical tolerance (ISO 2768-2) class K

Linear tolerance (ISO 2768-2) class M.

(***) Suggested position for hydraulic connectors.

(****) To calculate the minimum number of screws, use the following formulas:

- X (N° Stator screws) = Stack length * 0.04
- Y (N° Rotor screws) = Stack length * 0.089

Calculation for screws property class 8.8

The number of screws can be reduced using higher property classes.